



# SOLARIUS™

Extending the scope of **3D Surface Measurement Technology**

## **Polaris** High-end 3D surface metrology

Accuracy and precision down to the nanometer for the most demanding measuring tasks on complex surfaces

- 
- **Highest optical and digital resolution**
  - **Diffraction limited imaging**
  - **Reliable technology**
  - **ISO compliant roughness values**
  - **Non-contact measurements**
  - **Maintenance-free and robust**

**Solarius** is a leading provider of precision systems for non-contact surface inspection, measurement, analysis, and visualization.

**SOLARIUS™**



Our products combine high-resolution sensors with automated data acquisition systems and powerful analysis tools. Offerings range from desktop systems for off-line inspection, to semi-automated systems for fast, precise measurements, to customized multi-station platforms for high-volume in-line inspection. Our design philosophy focuses on standard products as well as customized solutions to best meet specialized requirements.

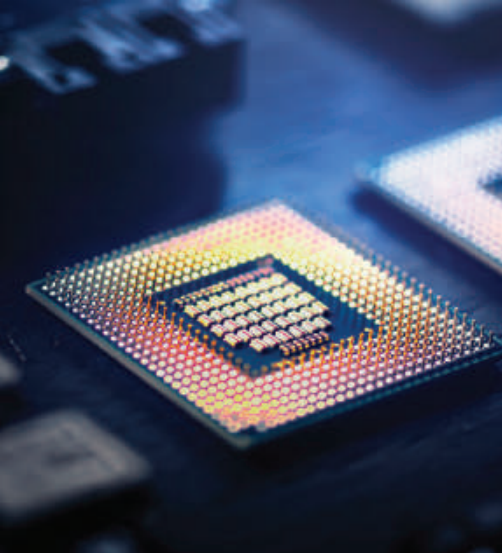
This process starts with understanding metrology challenges and budget constraints, followed by in depth analysis by our application and development engineers.

Customizing data acquisition software, analysis tools, and user interfaces are part of our approach to solve unique metrology application tasks.

Solarius corporate office and product development center are headquartered in San Jose, California. Our global entities and operations for sales, application engineering, customer support, and product development are based in China (Shanghai), Europe (Munich and Essen) and India (Pune). Augmented by our international partner network Solarius oversees an installed base exceeding 2,000 active metrology systems worldwide.



Solaris target markets such as **medicine**, **power supply**, **consumer electronics** and the **semiconductor** industry.



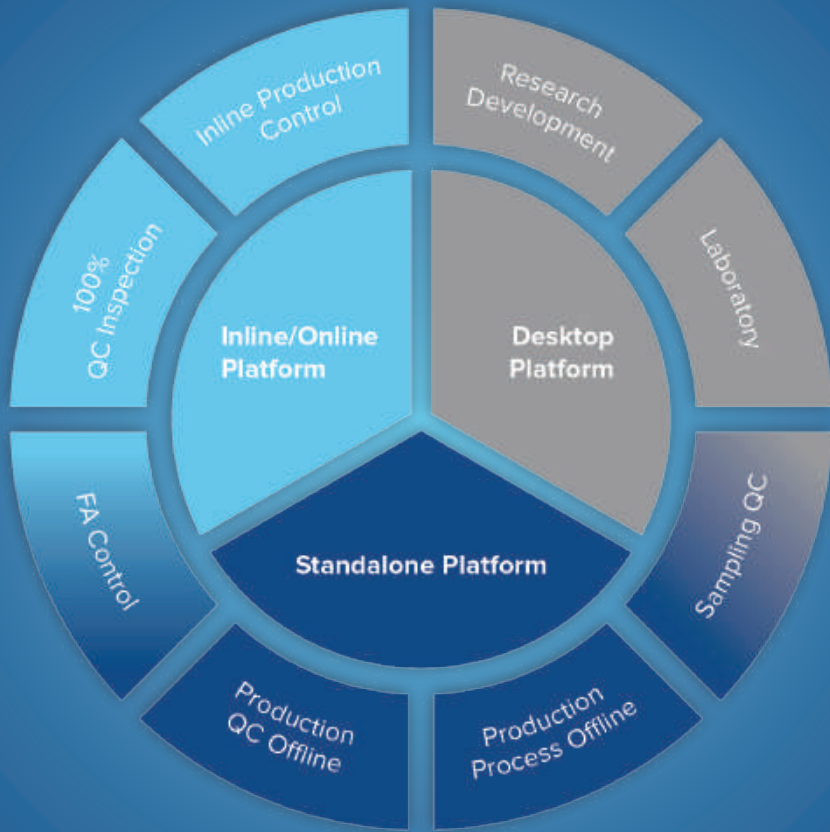
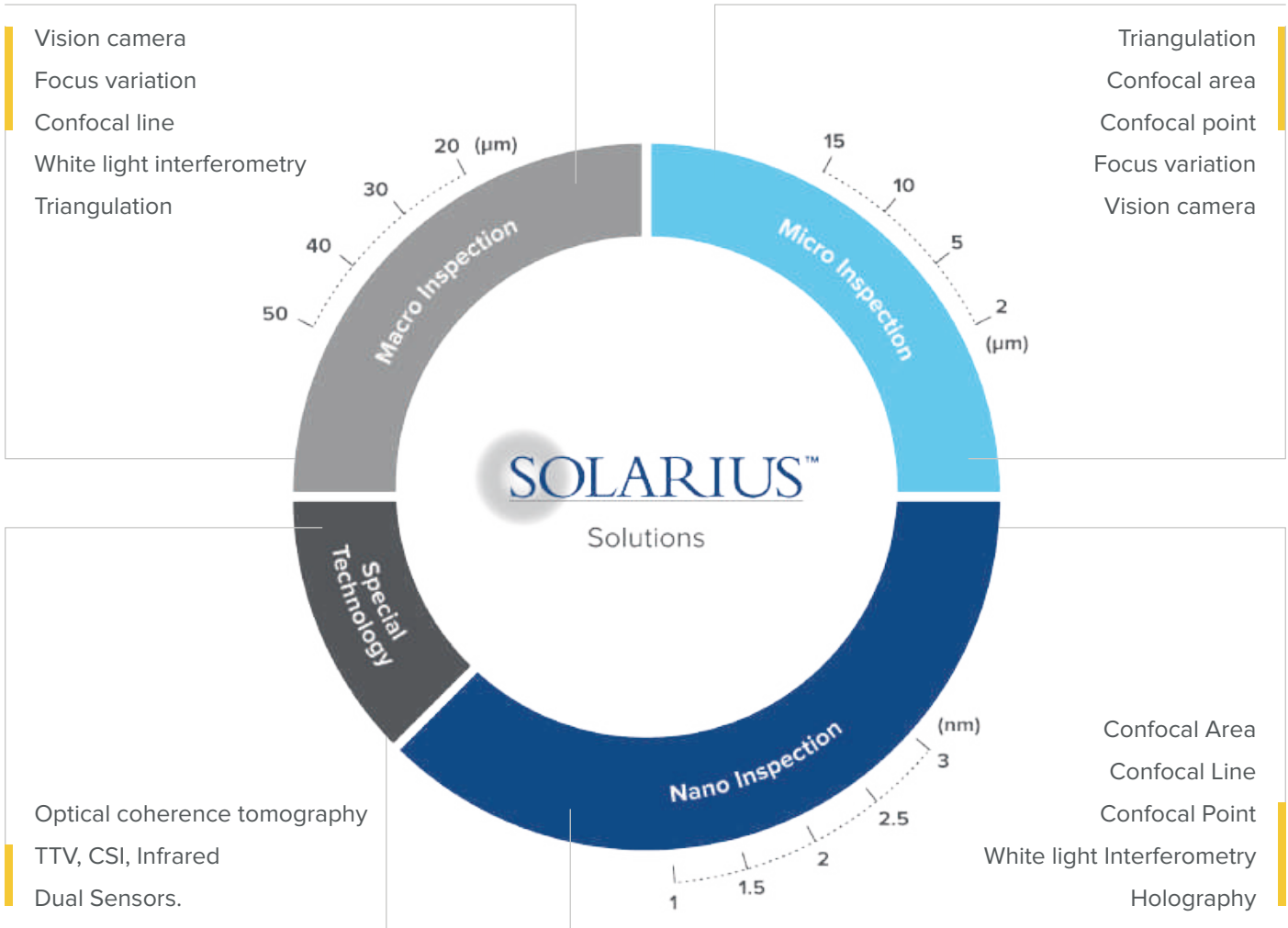
Specifically, the main focus of Solaris activities is on the challenges that regenerative energy supplies and the unstopably advancing integration of increasingly intelligent systems require.

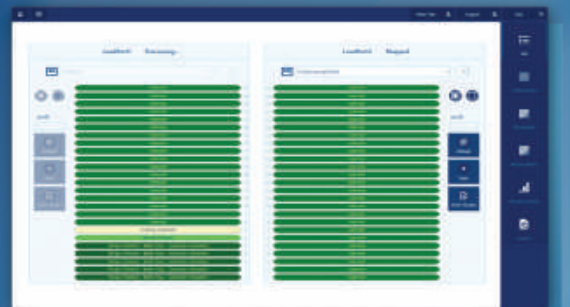
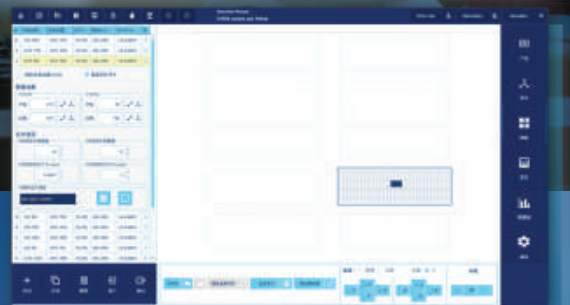
While innovations in medical technology are the basis for health and life, the semiconductor industry and energy supply are the starting point for every technological advance. Fuel cells enable emission-free mobility while hydrogen can effectively solve the storage problem of renewable energy. Micromechanical components and nanomaterials allow the fastest possible diagnoses and therapies and semiconductors are the basis for communication and control of almost every technological achievement of the present. While mobility is focused on range and availability and thus the requirements for energy efficiency and storage capacity will be addressed in the coming years with large investments, the semiconductor industry is still required to enable higher integration densities and computing power and with significant investments in new technologies to advance miniaturization to quantum systems.



In the medium to long term, Solaris' target markets are stable growth markets. Technological progress cannot and must not destroy the foundations of life any further, the integration and networking of communication and autonomous technology cannot be effectively and permanently halted even in case of uncontrollable events, and ultimately medical performance will continue to remain an unrestricted necessity, as current experience once again has demonstrated impressively.







# Solarius

## Powerful User Interface

- Sensor interchangeable without learning new UI
- Fully programmable for automatic inspection
- Algorithm to perform fully automatic data analysis
- Machine-learning for auto defect inspection

Compliant with SEMI, GAMP, FDA standard SECS-GEM interface.

# Automated **Metrology Solution**

Sample Alignment

## Standard Metrology Automation

Positioning

Data Acquisition

Data Analysis

Multi Data Analysis

Special Data Analysis

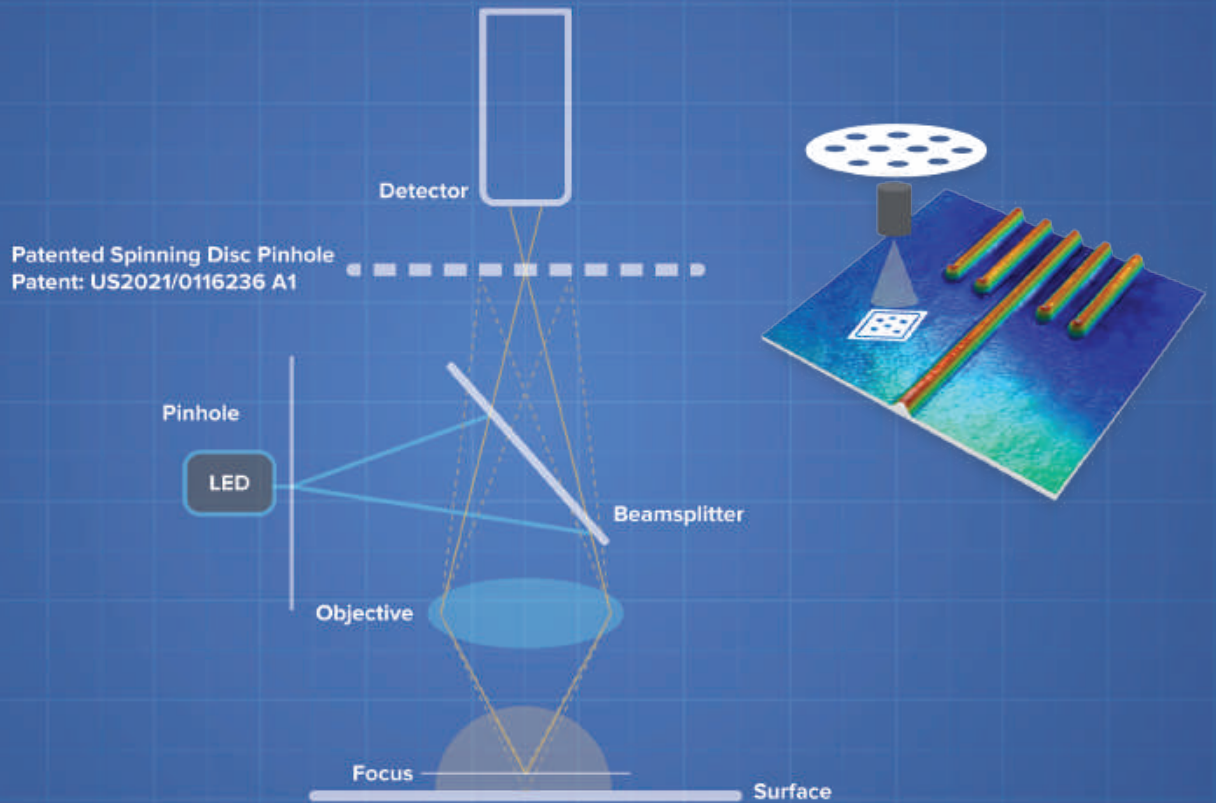
Auto Defect Inspection

**Presented data formats:** 3D image, 3D Models (Stp, Std), PDF, excel, csv, txt.

# Confocal Area Sensor

Axial Resolution: **1~25nm**

Lateral Resolution: **160~480nm**



In a confocal microscope, light is focused onto the surface. The reflected light is focused through the objective onto a pinhole before reaching the detector.

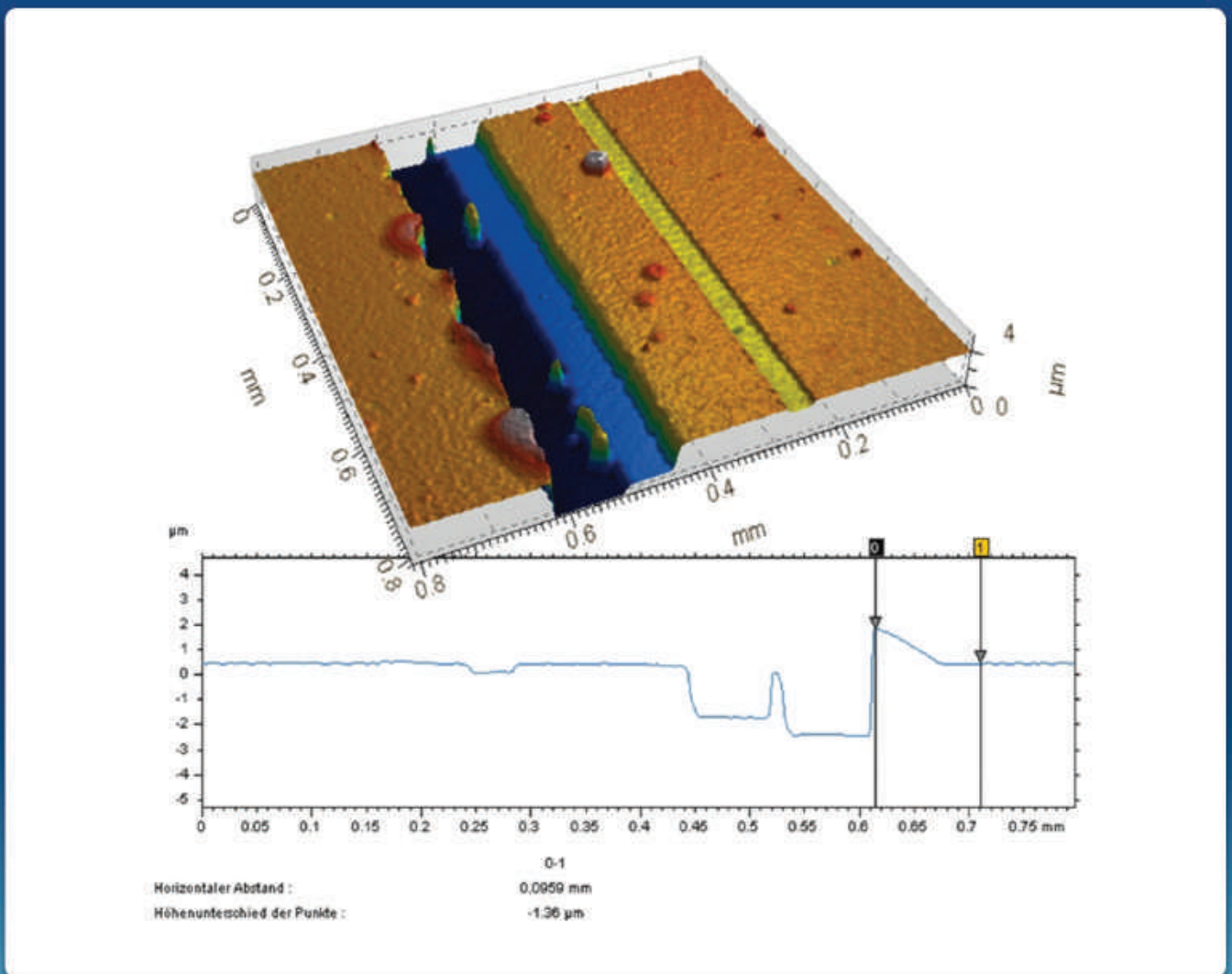
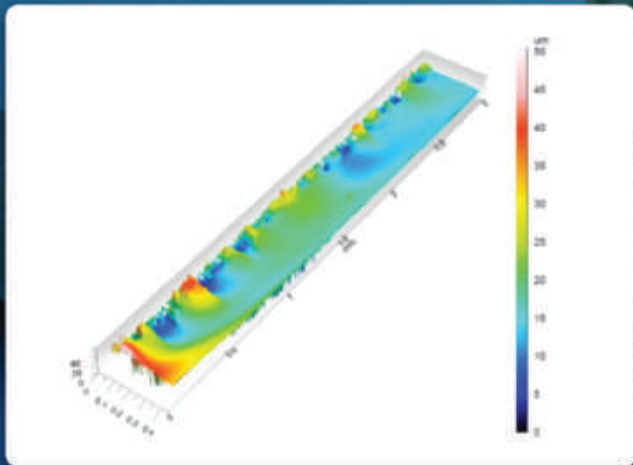
Only surface reflection light in focus reaches the detector through the pinhole.

The object moves up and down through the Z-Range and an algorithm detects the focus position on the surface.

In the “Confocal Area Microscope” the LED light is focused by a rotating pinhole disc and the objective onto the surface that reflects the light. Only surface reflections in focus pass the pinhole disc again through the holes – that light falls on the CMOS Camera. The rotation of the disc causes the entire sample surface to be scanned without gaps.

# Application

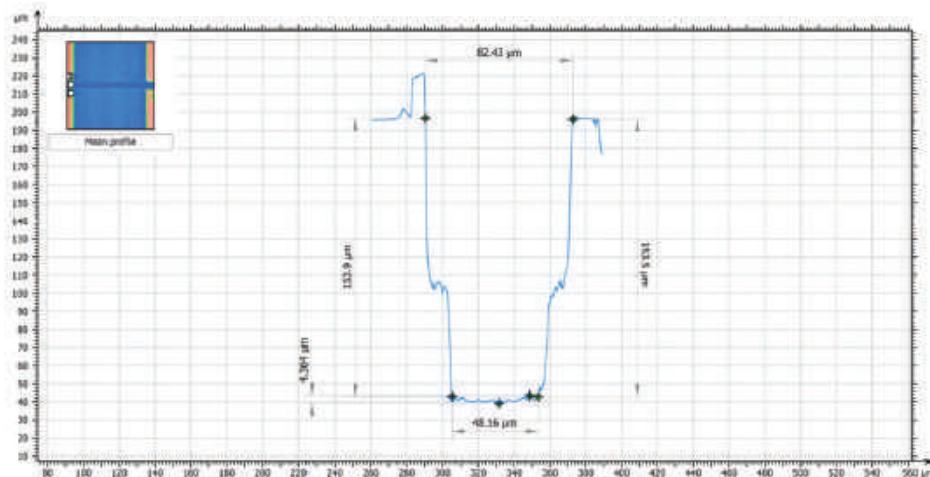
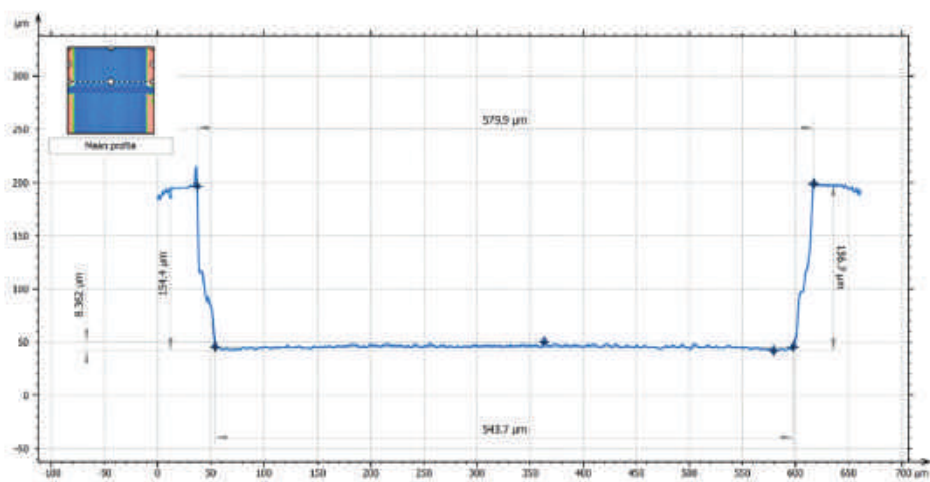
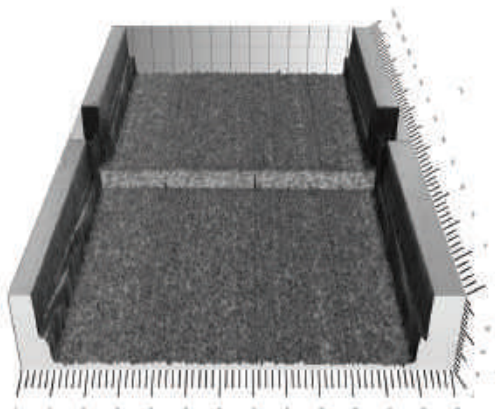
## Wafer Dicing Trench Inspection





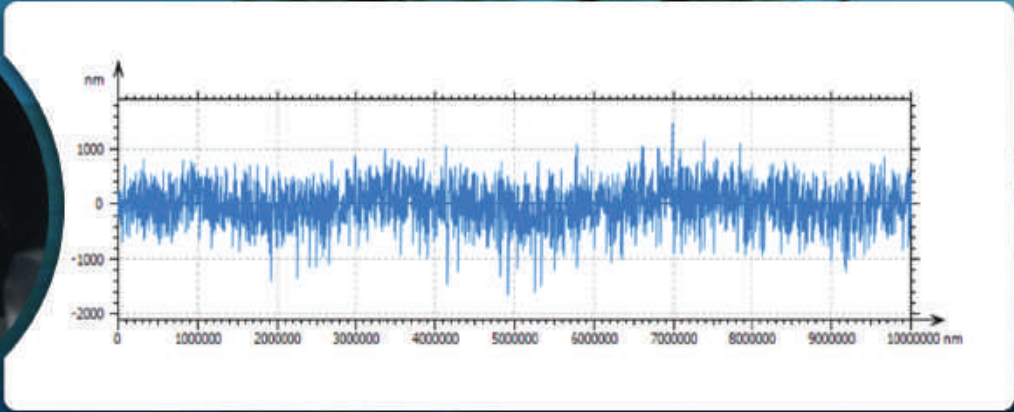
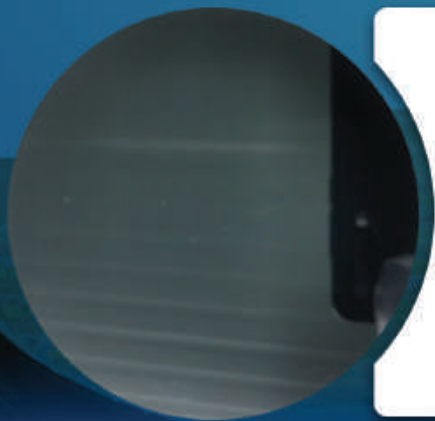
# Application

## Wafer Dicing Trench Inspection

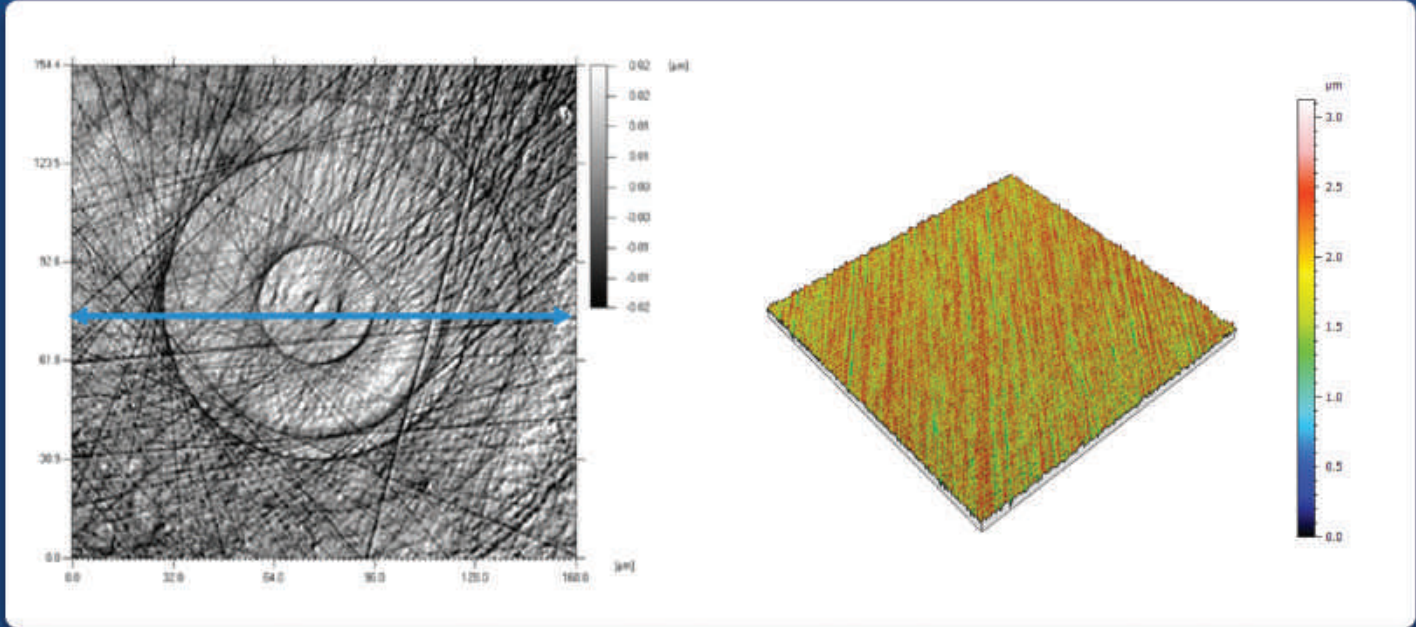


# Application

## Thin wafer Roughness Inspection



Parameters	Value	Unit
Length	1000	nm

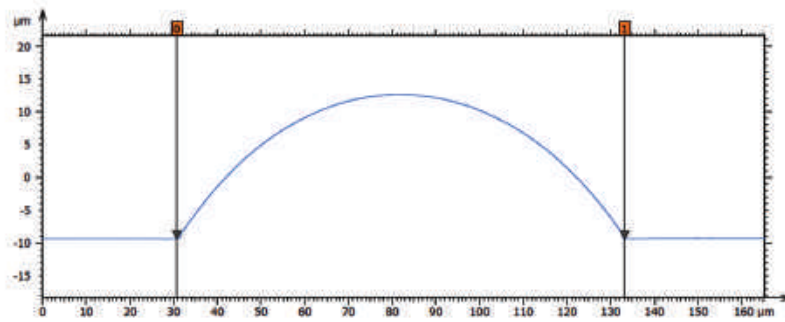
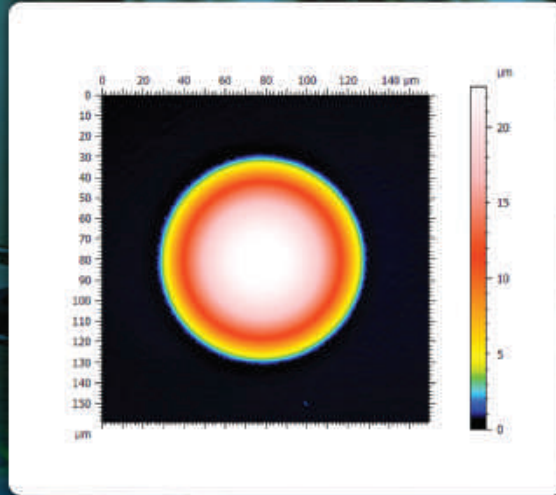
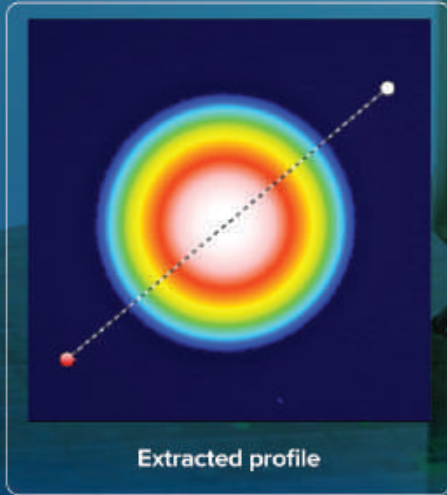


Ra = 0.005  $\mu\text{m}$   
Rz = 0.038  $\mu\text{m}$

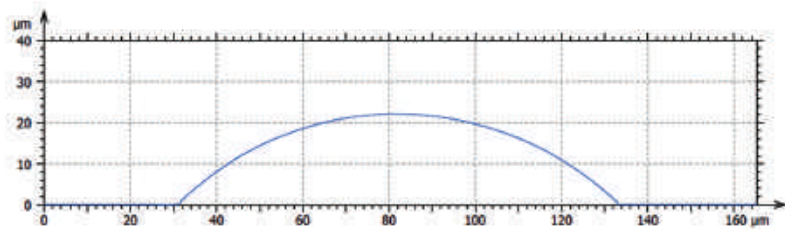
ISO 25178 - Primary surface			
F: [Workflow] Form removed (LS-poly 1)			
S-filter ( $\lambda$ s): Gaussian, 0.8 $\mu\text{m}$			
Height parameters			
Sp	1288	nm	Maximum peak height
Sv	1801	nm	Maximum pit depth
Sz	3089	nm	Maximum height
Sa	263.0	nm	Arithmetic mean height

# Application

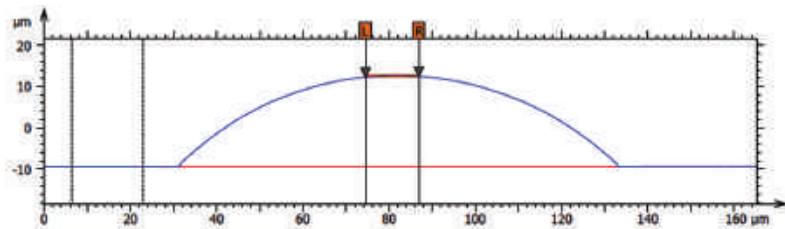
## Micro Lens Inspection



Parameters	0.1	Unit
Horizontal distance	102	$\mu\text{m}$
Radius	20.3	$\mu\text{m}$



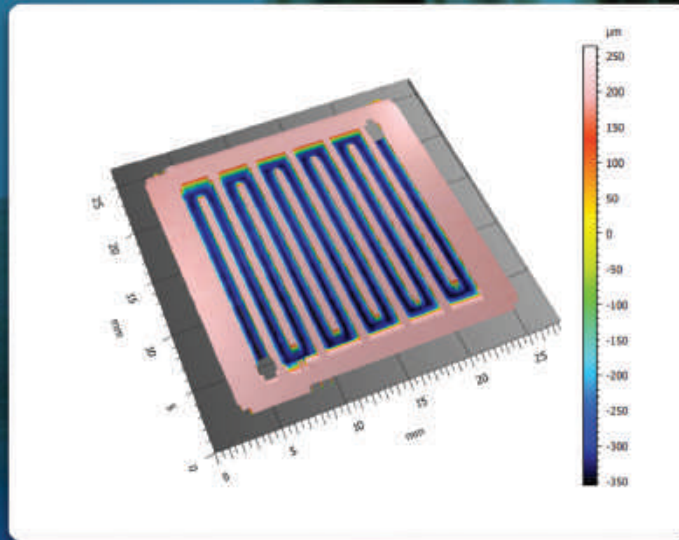
Parameters	Value	Unit
Length	165	$\mu\text{m}$



Parameters	Step 1	Unit
Width	12.4	$\mu\text{m}$
Maximum height	22.9	$\mu\text{m}$
Mean height	21.9	$\mu\text{m}$

# Application

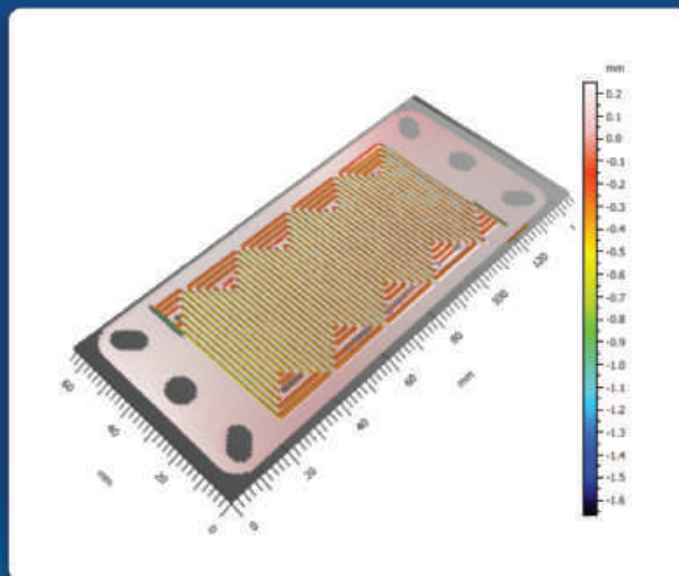
## Fuel Cell Bipolar Plate Inspection



ISO 12781

### Flatness Parameters

FLTt	14.24	µm	Peak-to-valley flatness deviation of the surface
FLTp	4.77	µm	Peak-to-reference flatness deviation
FLTv	9.47	µm	Reference-to-valley flatness deviation
FLTq	2.84	µm	Root-mean-square flatness deviation



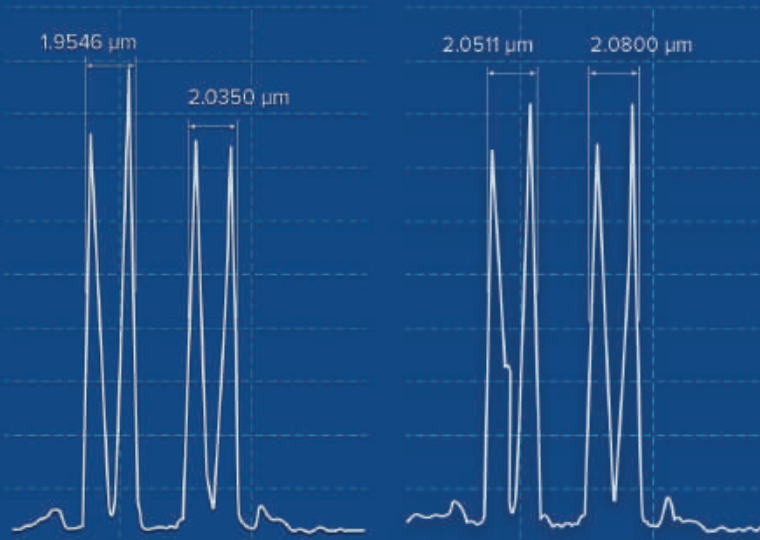
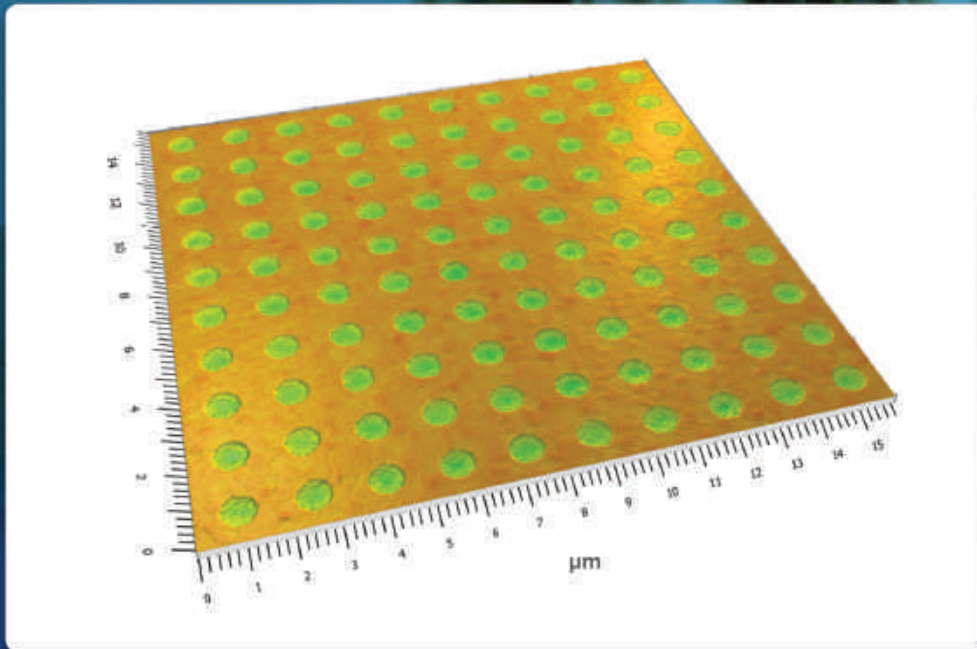
ISO 12781

### Flatness Parameters

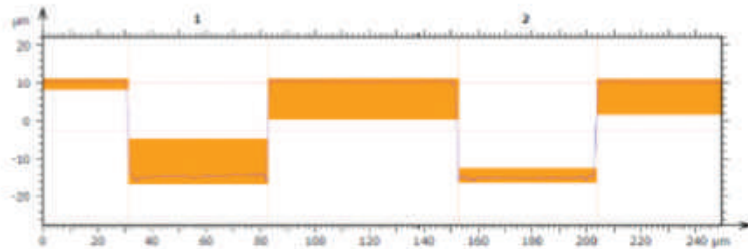
FLTt	192.42	µm	Peak-to-valley flatness deviation of the surface
FLTp	61.57	µm	Peak-to-reference flatness deviation
FLTv	130.85	µm	Reference-to-valley flatness deviation
FLTq	36.85	µm	Root-mean-square flatness deviation

# Application

## Micro Via Inspection



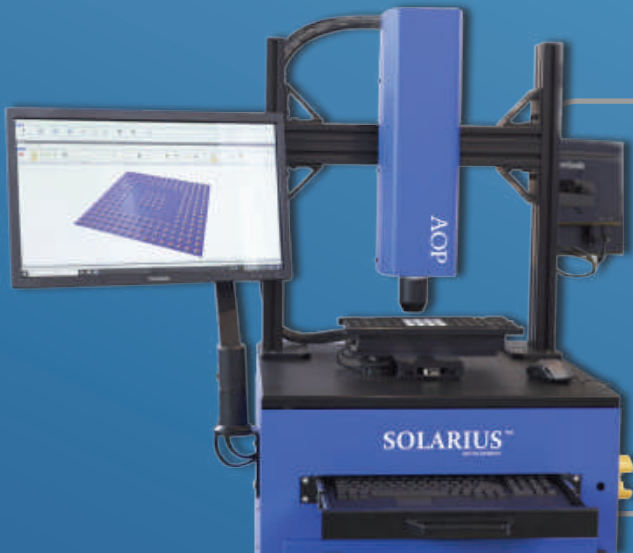
Profilansicht



Parameter	Erwart.	Stufe 1	Stufe 2
Breite	µm	51.4	50.7
Maximale Tiefe	µm	25.4	25.0
Durchschnittstiefe	µm	24.7	25.4

## The Polaris

Features a comfortable and precise automated X/Y positioning unit with 150 mm x 150 mm travel range and height measuring range of 400m.



## The Polaris Plus

A customizable standalone tool design for semi-production used. Customization are based on customers needs such stage size, measurement range, special fixtures, and dual sensors technologies.

Fully automated solution with multiple sensors technology.

Compatible with different sample handling requirement.



# Technical Data Polaris

Incredibly fast **3D inspection** makes Polaris unrivaled in price, accuracy, and speed.



## Confocal Area Sensor

Objective	Numerical Aperture	Working Distance (mm)	Field of View ( $\mu\text{m}^2$ )	Spatial Sampling (nm)	Optical Resolution (nm)	Maximum Slope ( $^\circ$ )	Vertical Resolution (nm)
10x	0.30	17.5	1,312 x 1,312	640	480	14	25
20x	0.45	4.5	656 x 656	320	320	21	8
20x ELWD	0.40	19.0	656 x 656	320	360	24	12
50x	0.80	1.0	270 x 270	132	180	42	3
50x LWD	0.80	2.0	270 x 270	132	180	42	3
50x ELWD	0.60	11.0	270 x 270	132	240	37	5
100x	0.90	1.0	135 x 135	66	160	51	2
100x LWD	0.90	2.0	135 x 135	66	160	51	2
100x ELWD	0.80	4.5	135 x 135	66	180	42	3
150x	0.95	0.3	87 x 87	42.5	150	71	1
150x LWD	0.90	1.5	87 x 87	42.5	160	51	2

## System Configuration

Setup	Desktop system
Lateral measurement range / travel range	150mm x 150mm / 100mm x 100mm
Load capacity	max. 10kg
Vertical travel range	up to 100mm
Dimensions [WxDxH]	580mm x 500mm x 1,020mm
Weight	65kg
Supply voltage	0.100-240V, 50-60Hz
File formats	SUR, TXT, CSV
Computer	Desktop PC incl. monitor
Software	SolarScanNT, SolarMap, customized analysis software*

\*Customer and application specific

# SIMP



## System Configuration

Available Sensor Technologies	<ul style="list-style-type: none"> <li>Confocal point, line &amp; area sensors</li> <li>Interferometric point &amp; area sensors</li> <li>Triangulation point &amp; line sensors</li> <li>Focus variation and fusion technologies</li> </ul>
Standards applicable	SEMI, GAMP, FDA (optional)
SECS/GEM features	E4, E5, E30, E37, E39, E40, E87, E90, E94, E116, E84 AMHS
Hardware features	<ul style="list-style-type: none"> <li>Single / dual arm robots, ionizers</li> <li>Class 1 FFU modules, AGV adapters</li> <li>Edge grip, needle, bernoulli end effectors</li> <li>Air/N<sub>2</sub> burst modules for warpage wafer</li> </ul>
Media Supply	CDA, Vacuum, N <sub>2</sub> (optional) 220V 16A 50Hz, single phase
Lateral Working Range	400mm x 400mm
Vertical Working Range	400µm to 10mm
Lateral Resolution	0.042µm up
Vertical Resolution	0.1nm up



# SIMP compatibility

## Handling Module



E84 Sensor Provision  
for OHT

Side panel and Light  
Curtain for OHT Protection

E84 Sensor for AGV



# **SIMP** compatibility

## Load Port Configuration



**Cassette LP ISO RIGHT**



**Cassette LP with Tilting Mechanism ISO LEFT 1**



**Foup LP-300 ISO RIGHT**



**Open Cassette-200-LDR**



**Open Cassette LP (ISO LEFT)**



**Open Cassette-150**

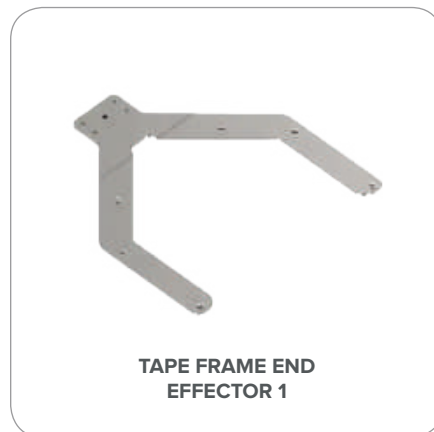
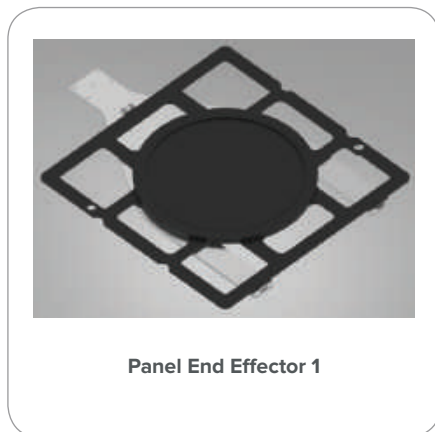


**SMIF LP with Open Clear Pod and Cassette 1**

# SIMP compatibility

## End Effector

1	Bernoulli End Effectors
2	Electrostatic (ESC) Grip End Effectors
3	Edge Grip End Effectors
4	Porous Chuck End Effectors
5	Vacuum Grip End Effectors
6	End Effectors with Friction Pads



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